

# Movement

Twitching, running, speaking, blinking.....

# What does the brain do?

The brain has some role in regulating hormones within the body (including self-regulation).

Other than that, all the brain does that we can see/record/measure, is **move muscles**.

Even language is only evident through movement (speech, writing, signs...)

Many (all?) of the basic principles of movement are held in common with other species.

Why move?

Food is not evenly distributed in most environments.

Resting may require a different environment to feeding

and, of course, reproduction.....



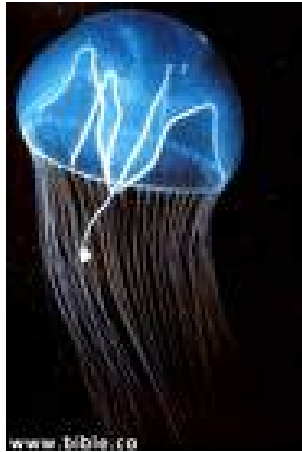
“The juvenile sea squirt wanders through the sea searching for a suitable rock or hunk of coral to cling to and make its home for life. For this task, it has a rudimentary nervous system. When it finds its spot and takes root, it doesn't need its brain anymore, so it eats it! It's rather like getting tenure.” (Daniel Dennett)

Inaccurate, but close. The sea squirt undergoes a metamorphosis, and digests its ganglion (bunch of nerves, kinda like a brain) in the process.

The ganglia are costly to maintain, and needed only for locomotion.

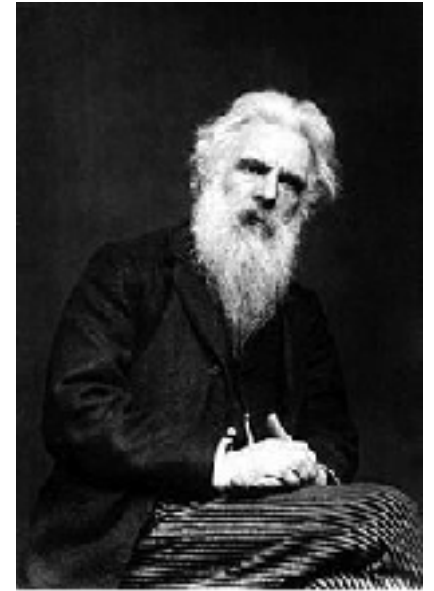
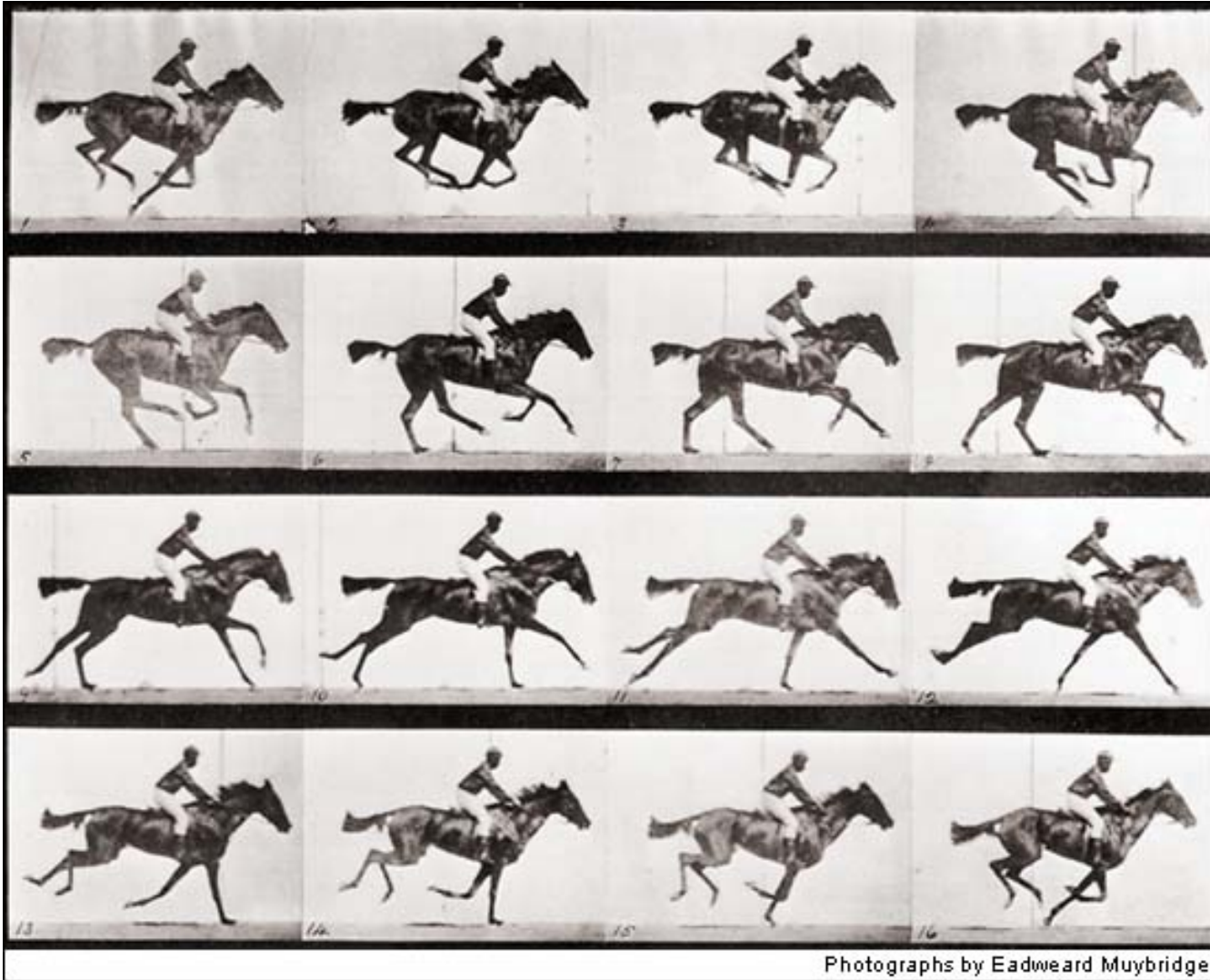


# Locomotion

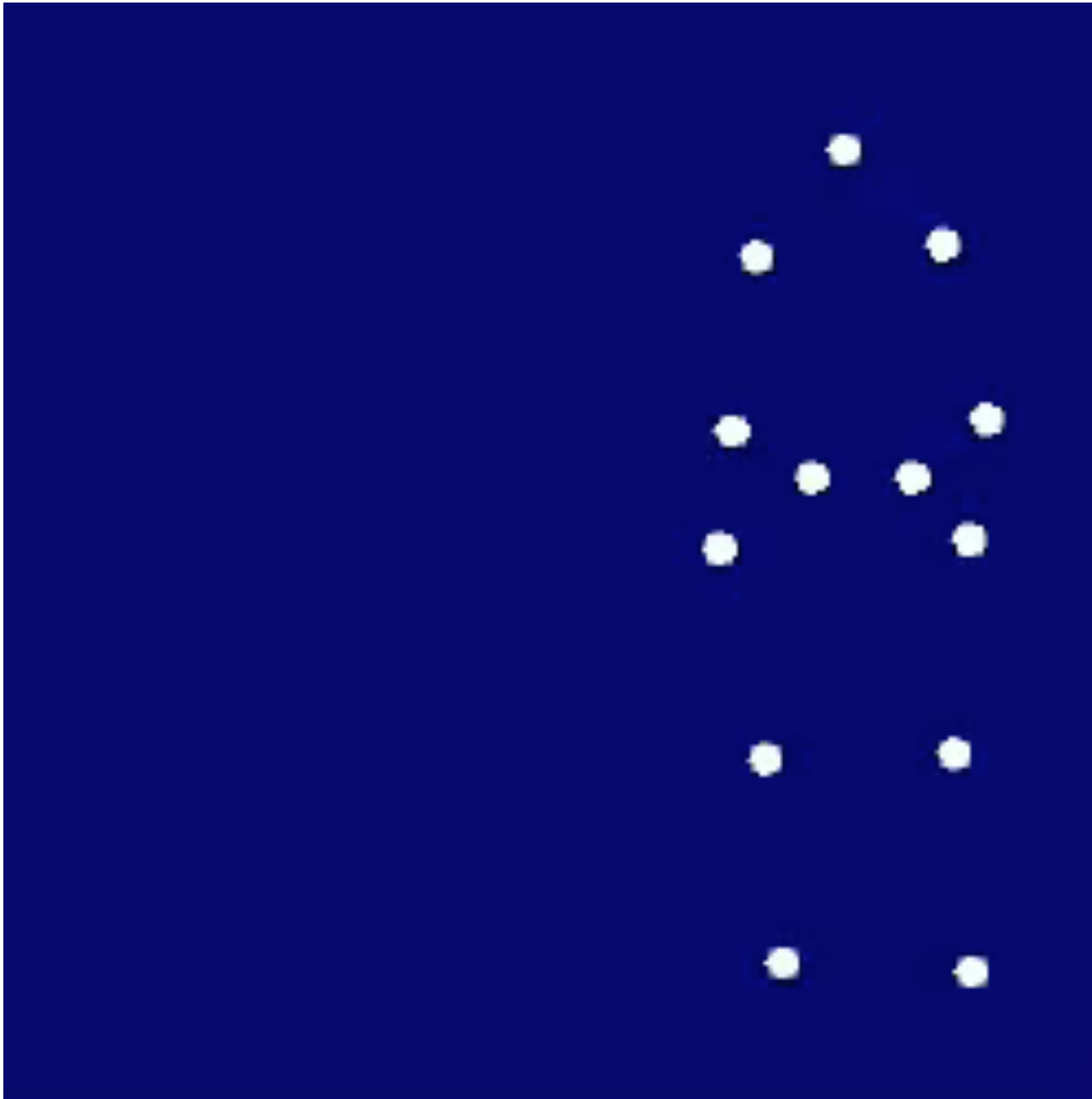


Where is the wheel in nature?

# 1872..1878: Does a horse have all four feet off the ground when galloping?

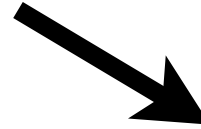


## Eadweard Muybridge

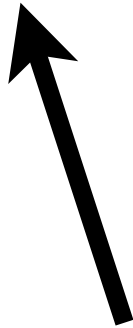


# What is **not** going on in locomotion?

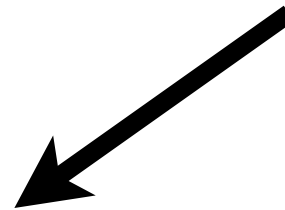
brain decides where foot  
should go next



brain figures out which  
muscle combination will  
get it there



brain commands those  
muscles to move just  
enough



Brains do not “decide”

Brains do not “figure stuff out”

Brains do not “see”

Brains do not “feel”

Brains are not people.



How many degrees of freedom does this puppet have?

How many things can be separately controlled?

# Degrees of Freedom

If we consider the brain to be controlling everything in movement, how many 'things' is it controlling?

7 degrees of freedom in the *joints* of one arm



Elbow: hinge joint (1 degree of freedom)



Shoulder: 3 d.o.f. (latitude, longitude, rotation)



Wrist: 3 d.o.f. (side to side, up down, rotation)



Each joint movement is controlled by multiple muscles (more degrees of freedom)

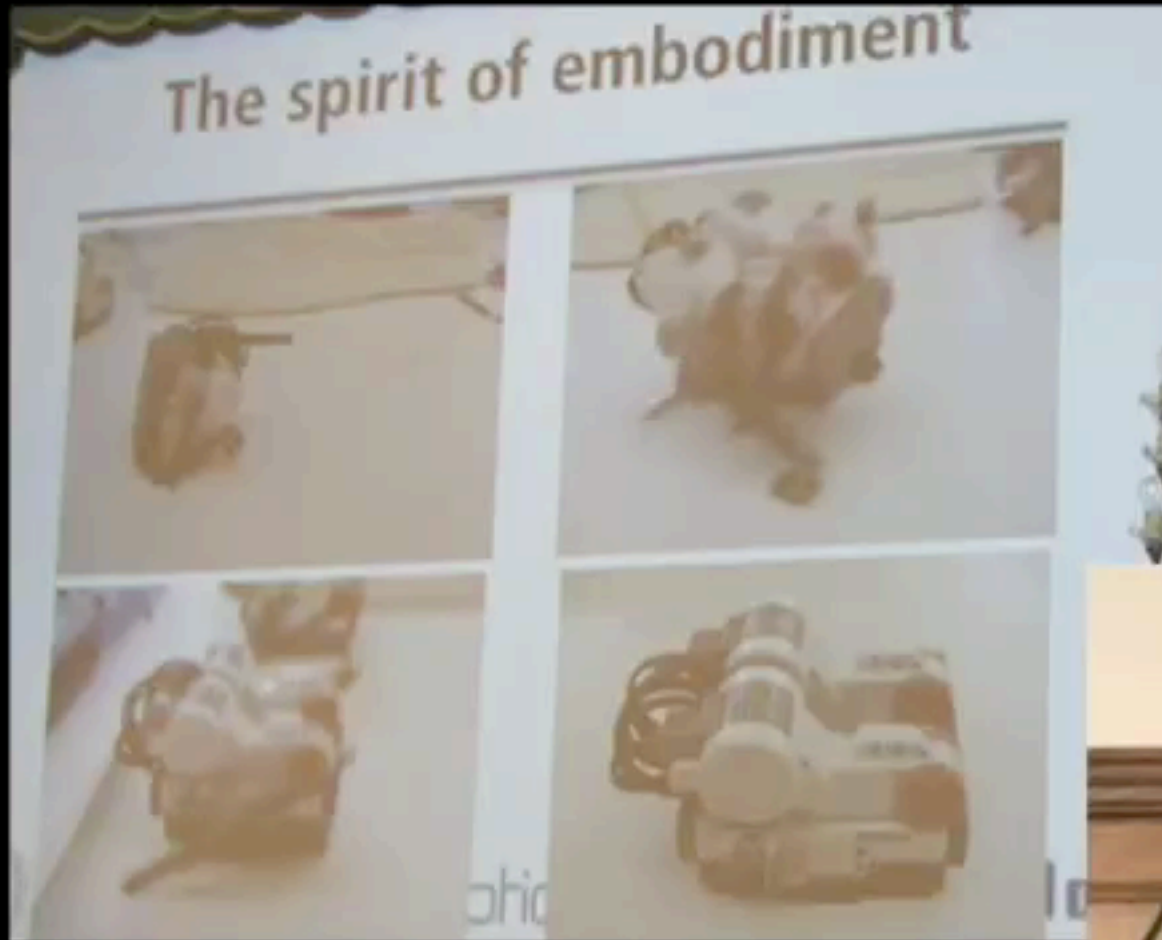
Each muscle consists of individual packages (yet more...), which break down even further.... (yet more....)

There are too many individual degrees of freedom for each to be separately controlled.  
(Nikolai Bernstein, Russian physiologist)

Body components move in a coordinated fashion, not as independent units

We tend to think intuitively that all behaviors arise from controllers.

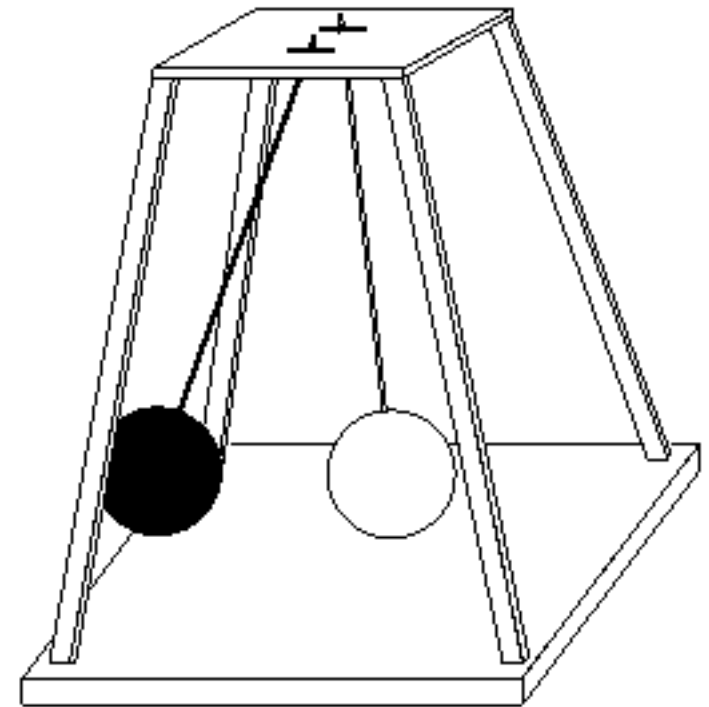
The study of coordinated movement suggests otherwise.



Rolf Pfeifer illustrates 1 controller with 3 behaviors using  
Lego MindStorms.  
Full video here: <http://vimeo.com/28811223>

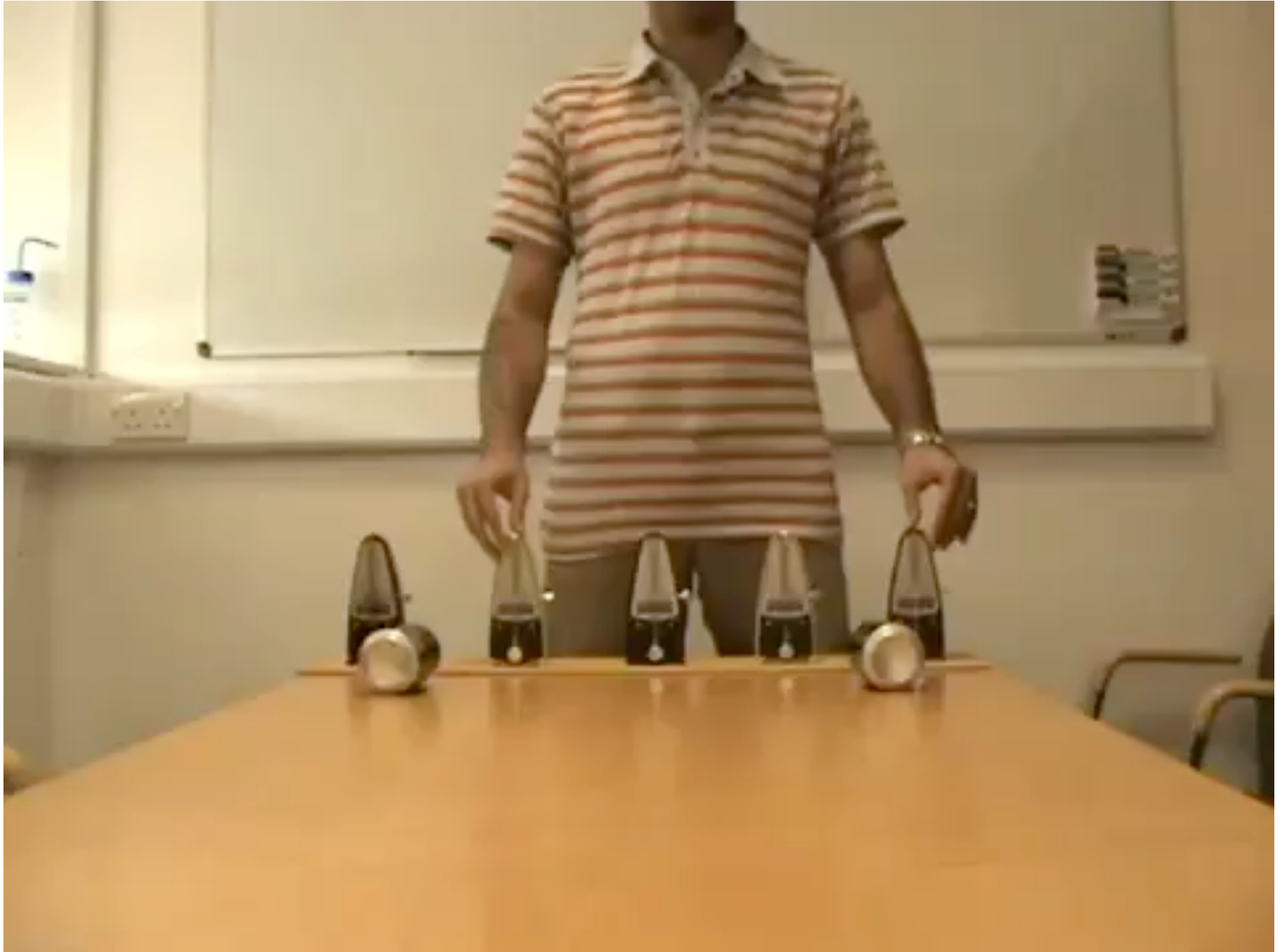
Bodies are physical things. They have physical properties (mass, inertia, etc). We need to consider the physics of bodies and the physics of locomotion. These problems are not dis-embodied!

## Oscillation



- Oscillations are periodic processes
- Position within one cycle is measure in *phase*
- Phase conventions include  $[0..1]$ ,  $[-\pi..\pi]$ ,  $[0..2\pi]$ .
- Two periodic processes may become *entrained* or *coupled*, as when 2 pendula swing in synchrony.

# Entrainment Demonstrated





The video illustrates the process of *entrainment*, whereby the cycles of individual metronomes become yoked together into a higher-level pattern.

You can also hear how the intrinsic oscillation of the individual metronomes “seeks” to assert itself against the emerging pattern.

Models of entrainment allow us to capture both individual autonomy, and collective patterning

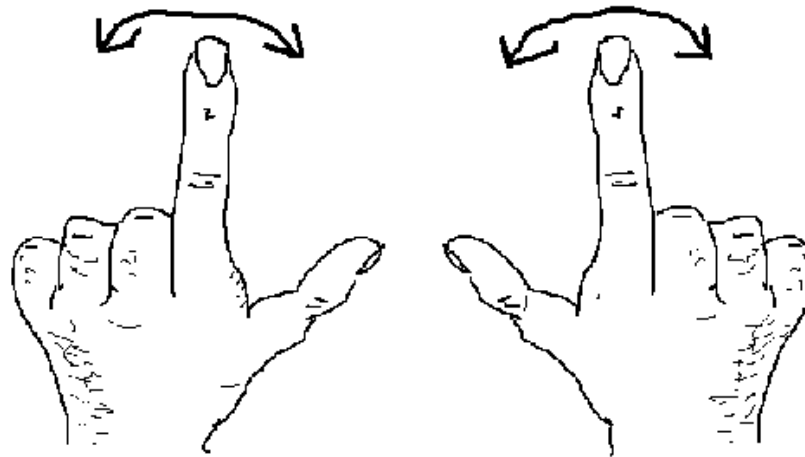


- There are simple regularities underlying the coordination of the limbs in *all* locomoting animals

Sometimes, a simple model system can help to uncover deep regularities.

# Coordination Dynamics: Scott Kelso and co-workers

## A **model system** for studying coordination

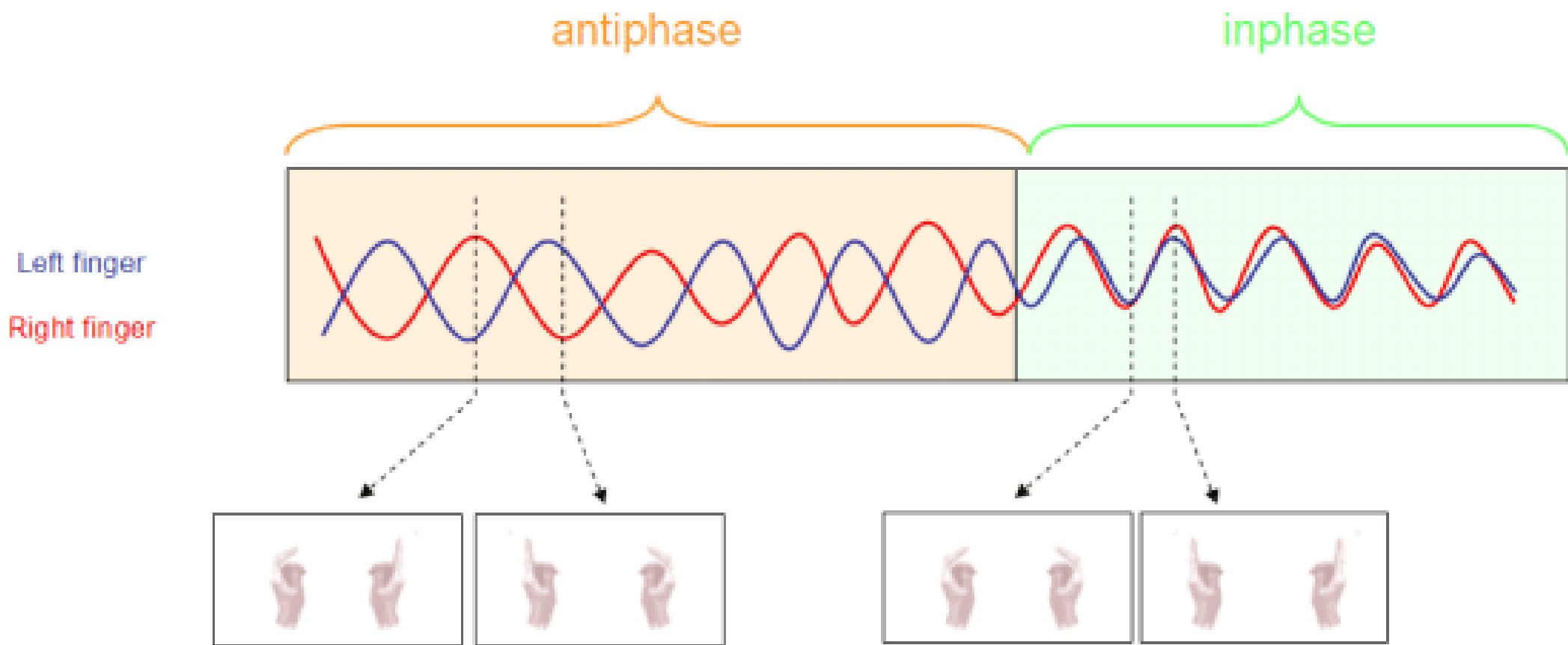


in phase

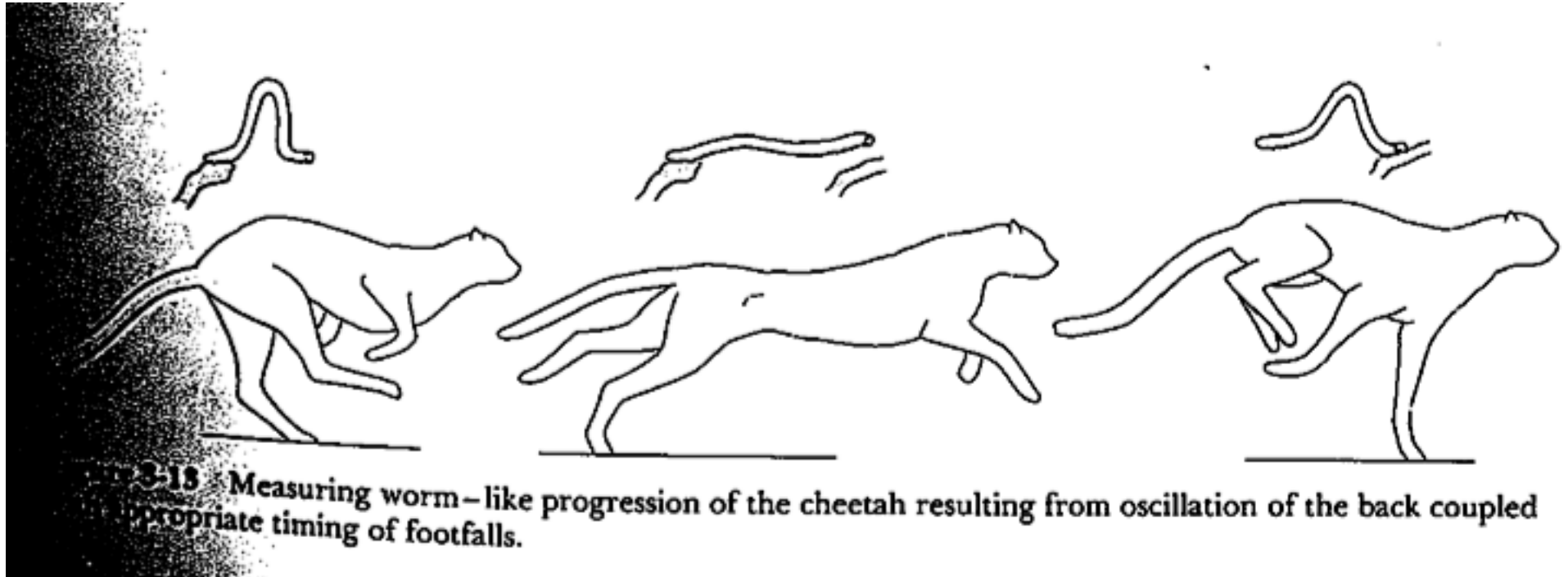
antiphase







- Two stable modes at moderate speed: in phase, and anti-phase
- transition to a single mode (in phase) at fast rate
- No comparable transition as rate is reduced
- Increase in variability shortly before the transition (critical fluctuations)
- Model system for studying coordination



Similar principles govern the form of locomotion in the inchworm and the cheetah.



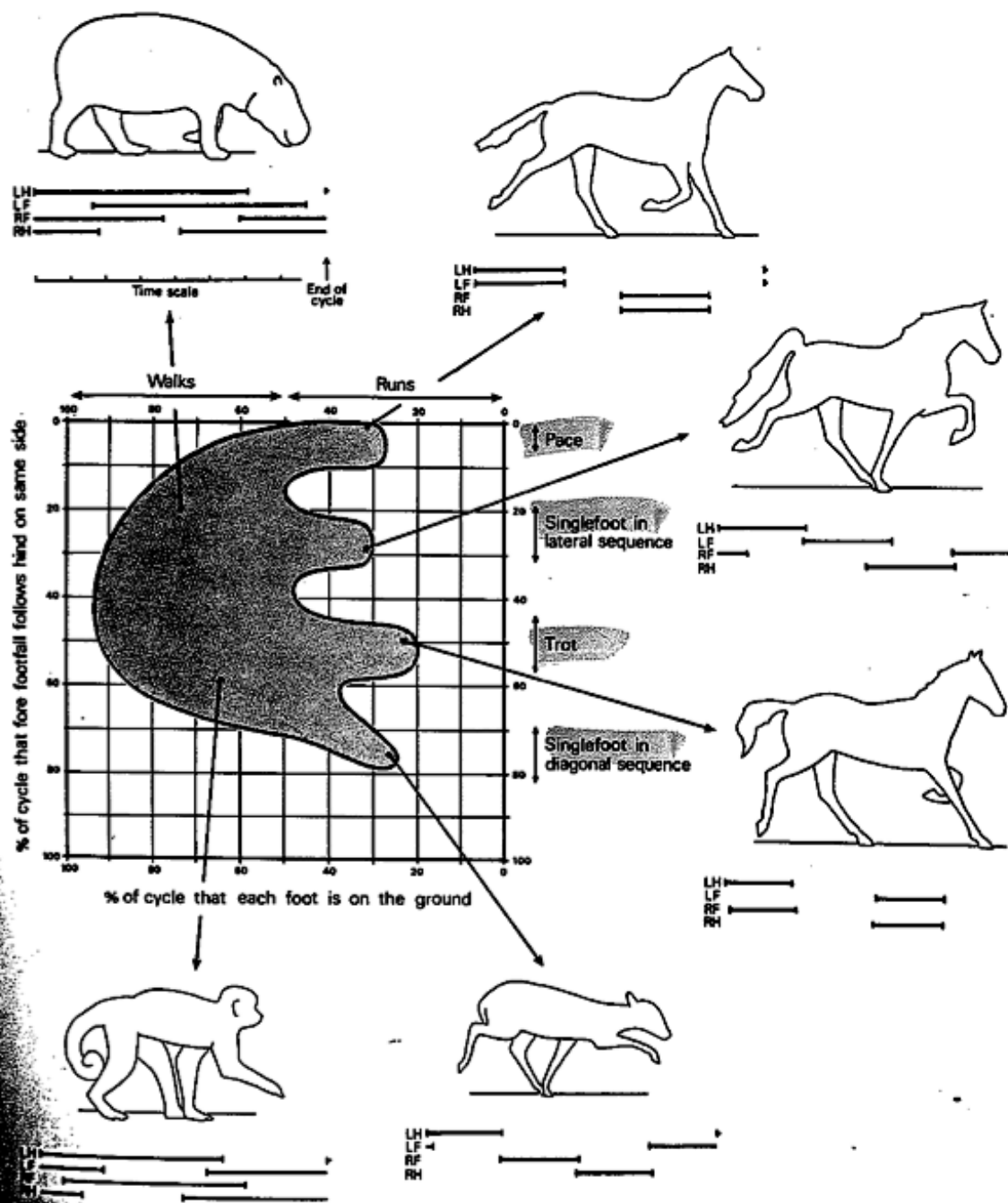
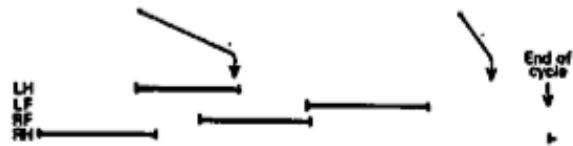
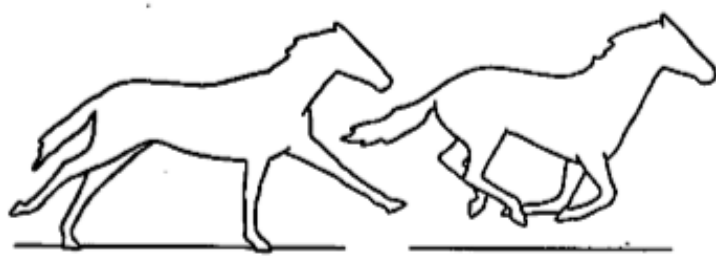
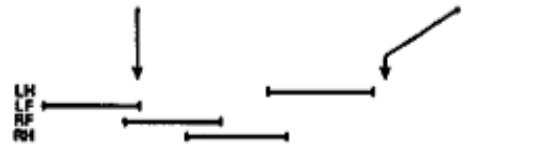
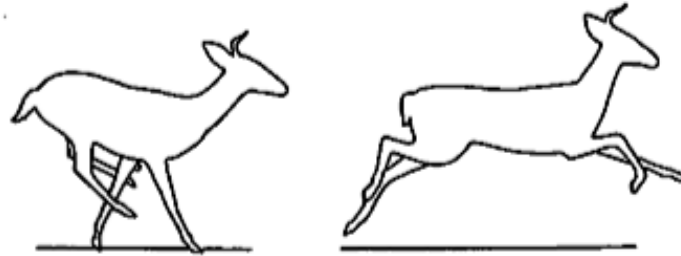


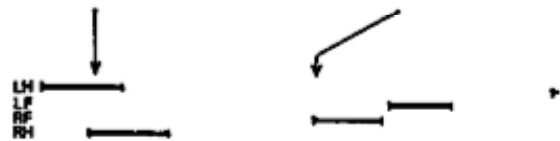
Figure 3-2 Symmetrical gaits as defined by the duration of contacts with the ground and the phase relationship of fore and hind feet. The outlined area encloses nearly 1200 plots for 156 genera, including amphibians, reptiles, and 16 orders of mammals. For the seven gaits recorded, a pigmy hippopotamus, three horses, a kangaroo, and a monkey are shown at the instant the left hind foot strikes the ground. Gait diagrams indicate the timing and durations of the respective contact intervals. Time scales (upper left) for the different animals are independent. H = hind; F = fore; R = right; L = left.



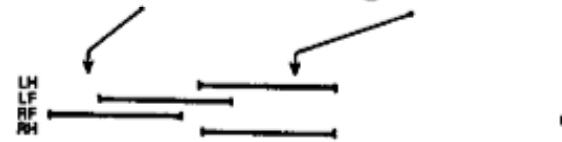
HORSE: Transverse gallop with gathered suspension



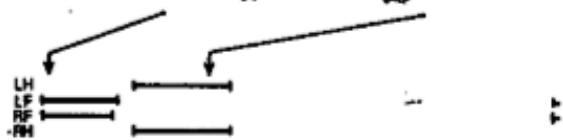
DEER: Rotary gallop with extended suspension



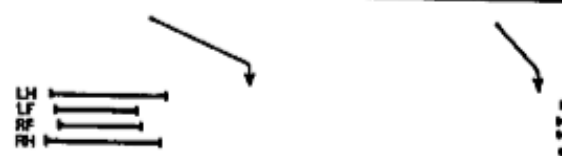
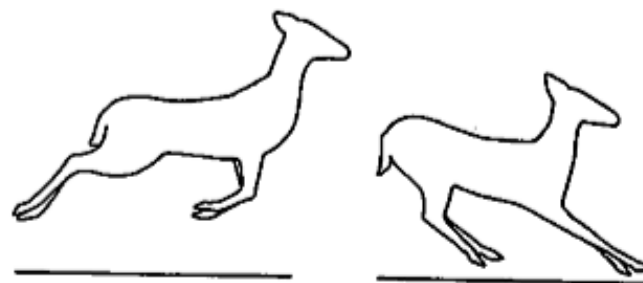
CHEETAH: Rotary gallop with both suspensions



WEASEL: Half bound with extended suspension



HOUSE MOUSE: Bound



DEER: Prong





# GOING AFRICA SAFARIS

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## **pronking springboks in Central Kalahari**

If an animal has several gaits at its disposal,  
is it free to choose one over the other at  
any time?

Or is there lawfulness here too, in the  
choice of gait?

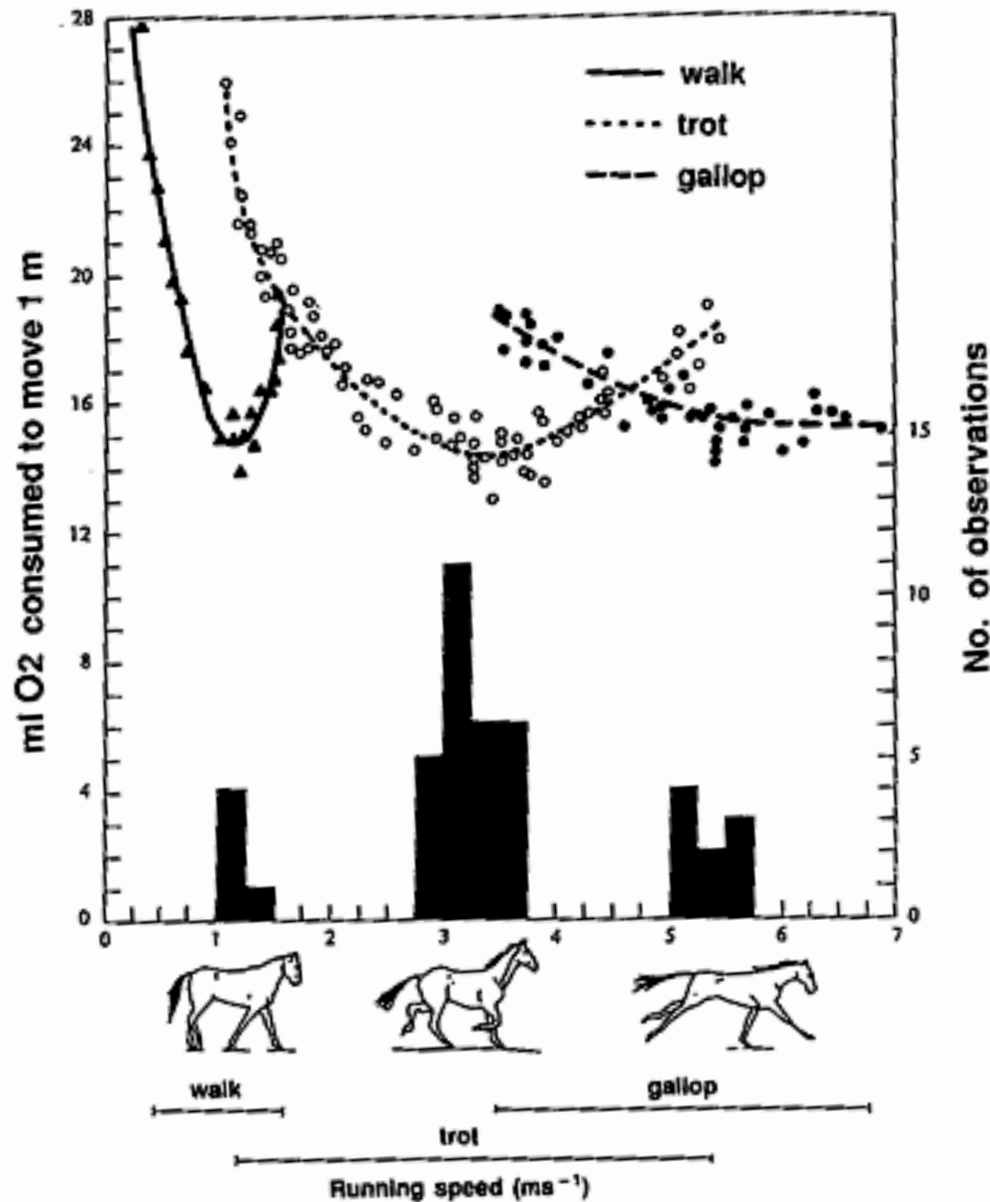


Figure 3.1 Oxygen consumption per meter moved and preferred speed (histograms) of walk, trot, and gallop of ponies. (Adapted from reference 4. Reprinted with permission)

Minimization of metabolic cost, indexed by oxygen consumption

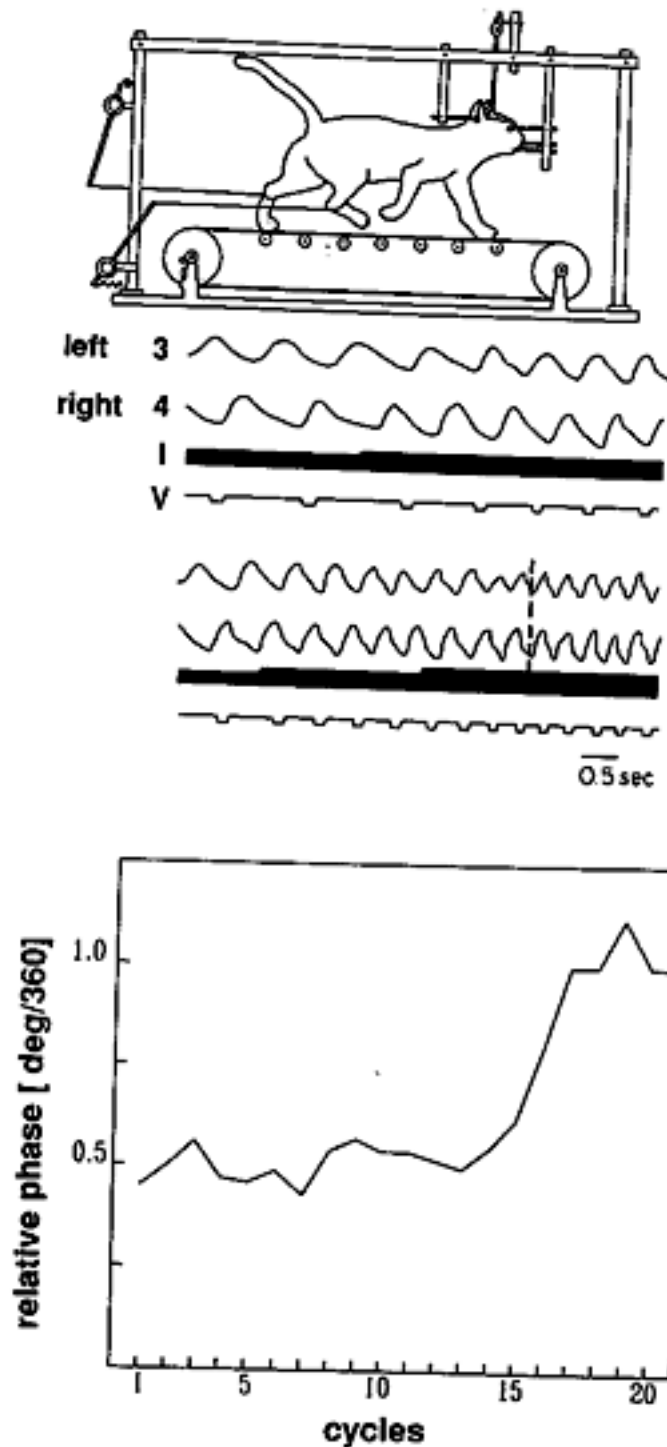
Hoyt and Taylor, Nature, 1981

Does the brain do everything in getting an animal to walk, or is it brain + body + simple physical constraints?

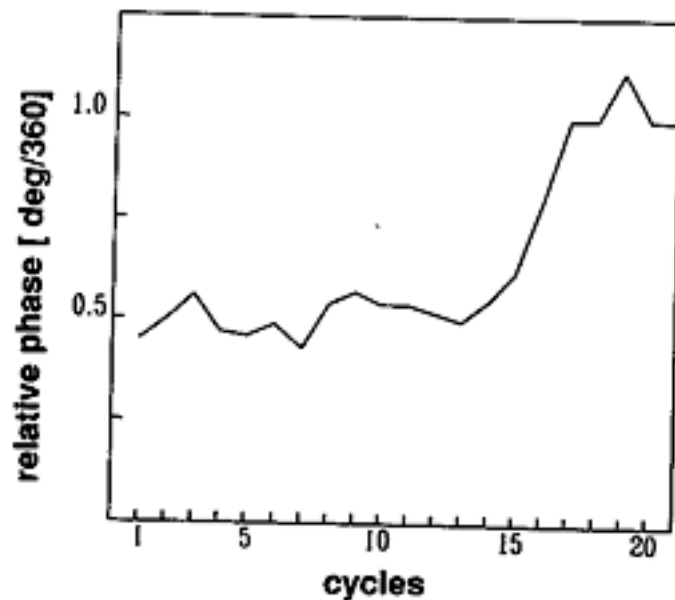
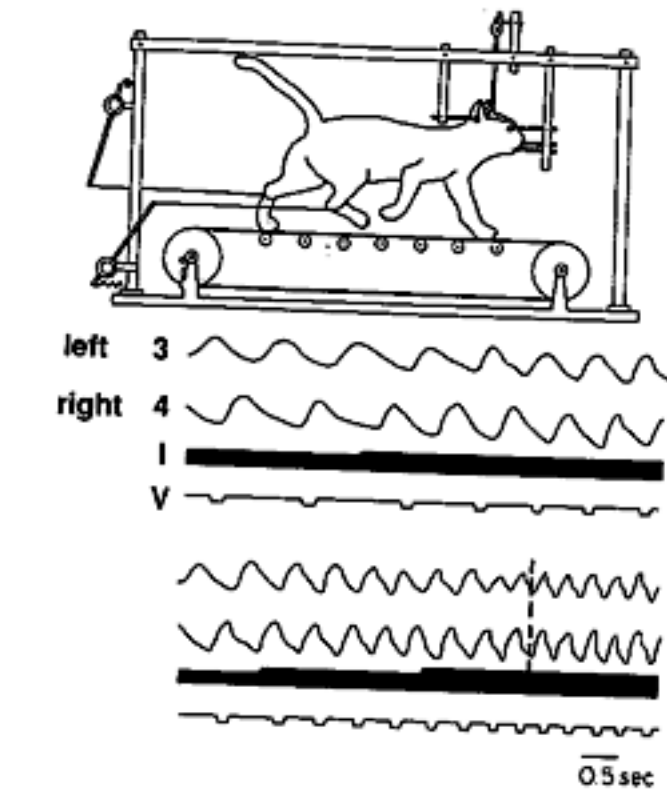
You could not make convincing walking movements without a firm ground support (e.g. when treading water in a pool)

Shik, Orlovskii and  
Severin, Biophysics,  
1966

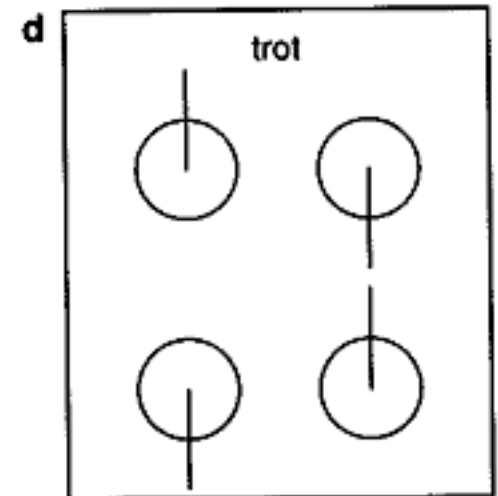
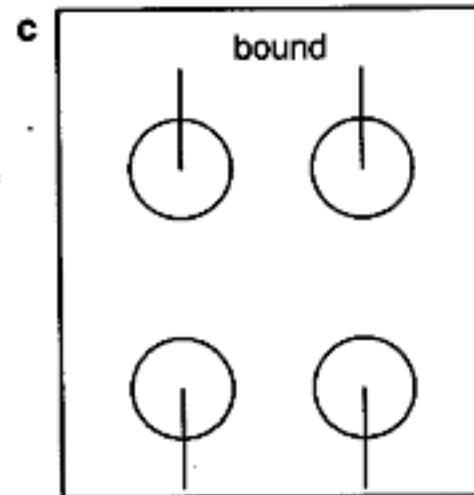
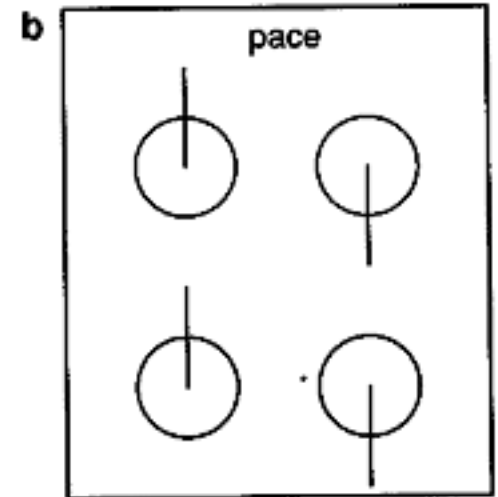
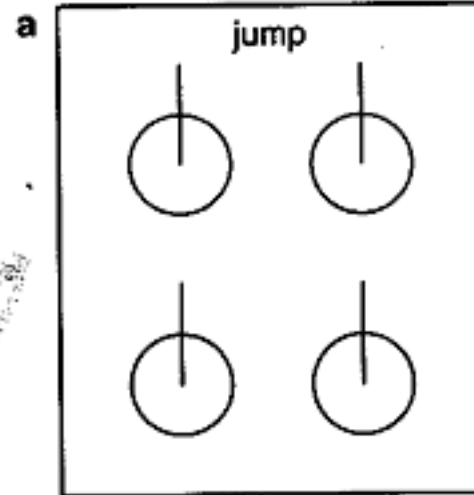
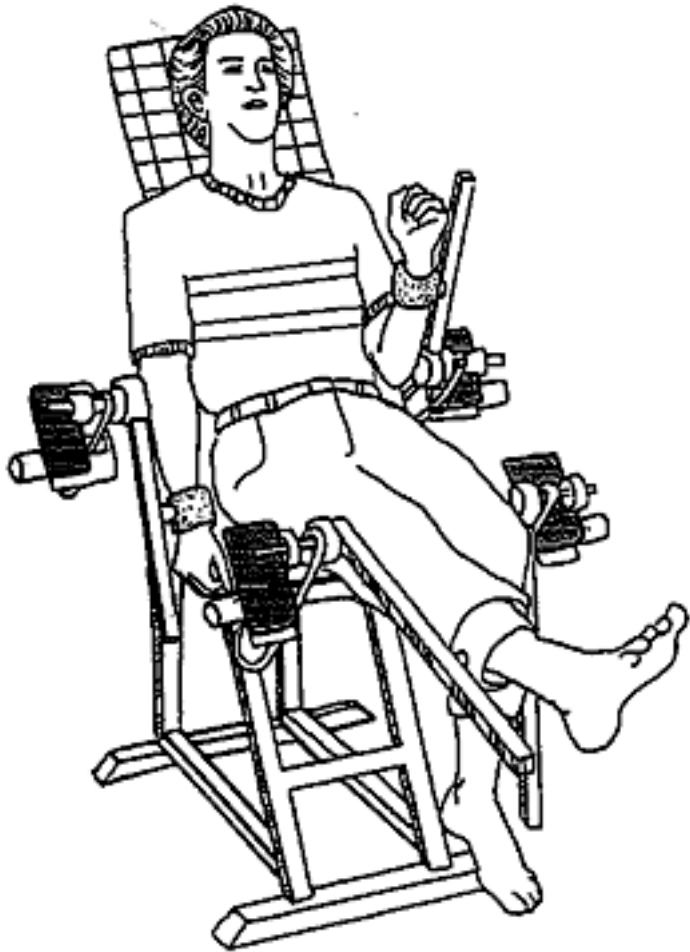
Mesencephalic cat: **self-  
organization**  
(= emergence)  
of an organized gait  
without cortical  
involvement

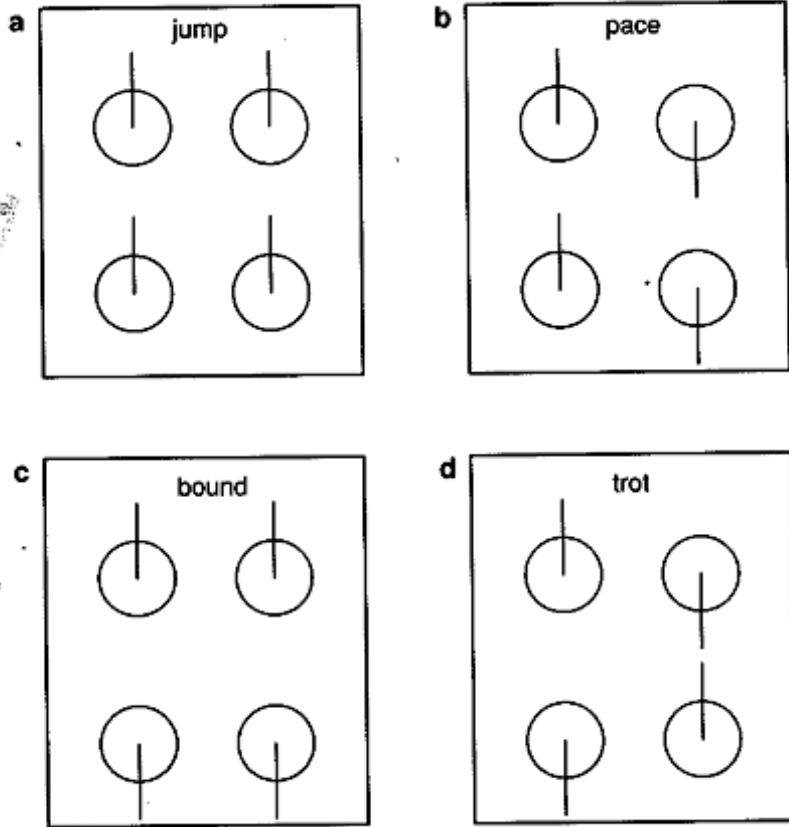






By stimulating a single site in the mid-brain (mesencephalon), changes in walking speed were induced, leading to abrupt gait changes at critical velocities.





When constrained to act as quadrupeds, humans display coordinative modes of the same kind as every other quadruped.



If pairs of legs are removed from a caterpillar, the resulting gait is immediately smooth, fluent, coordinated, and appropriate for the new number of legs.

# What is the brain doing here?

Coordination

Constraint

*Constraining* the many degrees of freedom of the body so that, in interaction with the environment, coordinated movement *emerges*.

In walking, it helps to temporarily construct a 'locomotion machine' in which the parts work together to bring about the goal of locomotion

**NOT control!!!!**

This 'locomotion machine' is:

- \* Task-specific
- \* Flexibly assembled
- \* More than the brain or brain + muscles
- \* Has less degrees of freedom than the sum of its parts

Within Action Theory/Coordination Dynamics, we call this a ***Coordinative Structure***. or Synergy.

You create *plucking* machines, *picking* machines, *scratching* machines, *catching/throwing* machines, *scrubbing* machines, and so on.....



A key concept here is the notion of “Emergence”.

When multiple components are subject to particular constraints, a pattern may emerge at the level above the components. This is emergence.

A tornado is an emergent pattern. Nobody designs or controls it.





The pinwheel is an emergent pattern. The puppies are the components.

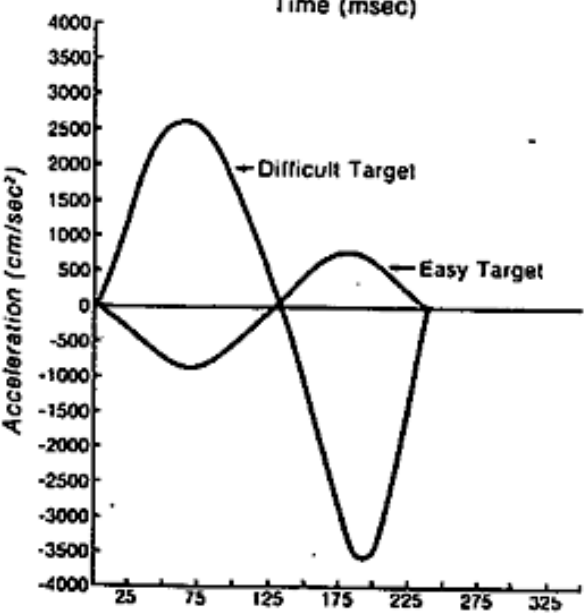
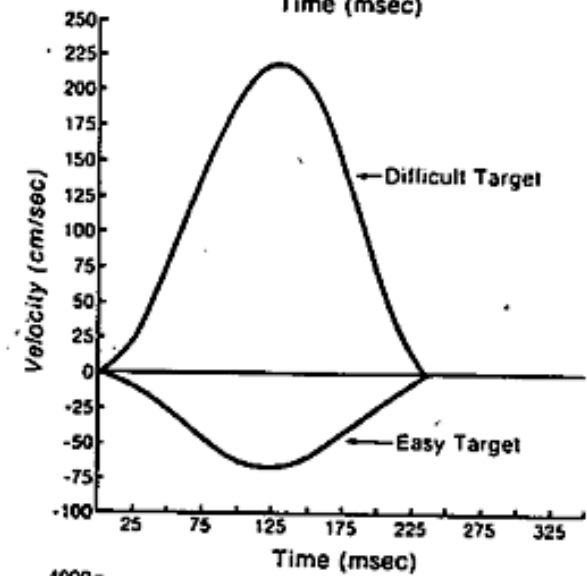
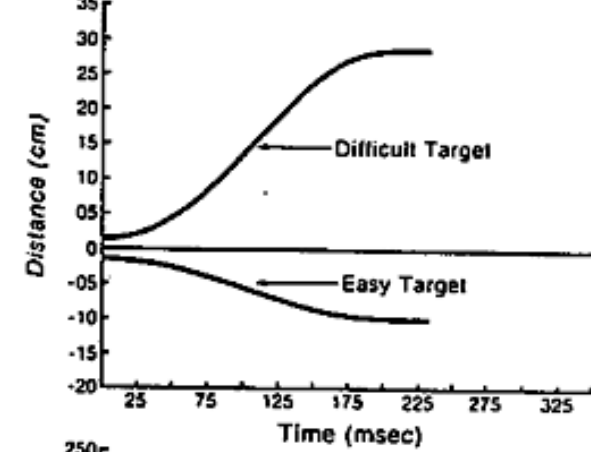
(If you are only looking at the notes, you are missing the fun of lectures, including this fine puppy video.)

# Science, 1979: On the Nature of Human Interlimb Coordination (Scott Kelso)

Total Response Time	Movement Time	Reaction Time	Left Target	Home Keys	Right Target	Reaction Time	Movement Time	Total Response Time
				• •	1 □	218	159	377
371	151	220	2 □	• •				
287	82	205	4 □	• •				
				• •	3 □	218	78	296
308	89	219	6 □	• •	5 □	224	85	309
403	166	237	8 □	• •		7 □	169	409
393	155	238	10 □	• •	9 □	246	133	379
383	140	243	12 □	• •	11 □	240	158	398

Fig. 1. Mean reaction time, movement time, and total response times for single- and two-handed movements varying in amplitude and precision requirements.

Each row corresponds to one experimental task. Subjects are asked to move, after a signal, from the midline to one or two targets.



..the brain produces simultaneity of action not by controlling each limb independently, but by **organizing** functional groupings of muscles that are **constrained** to act as a single unit

# Polyrhythms

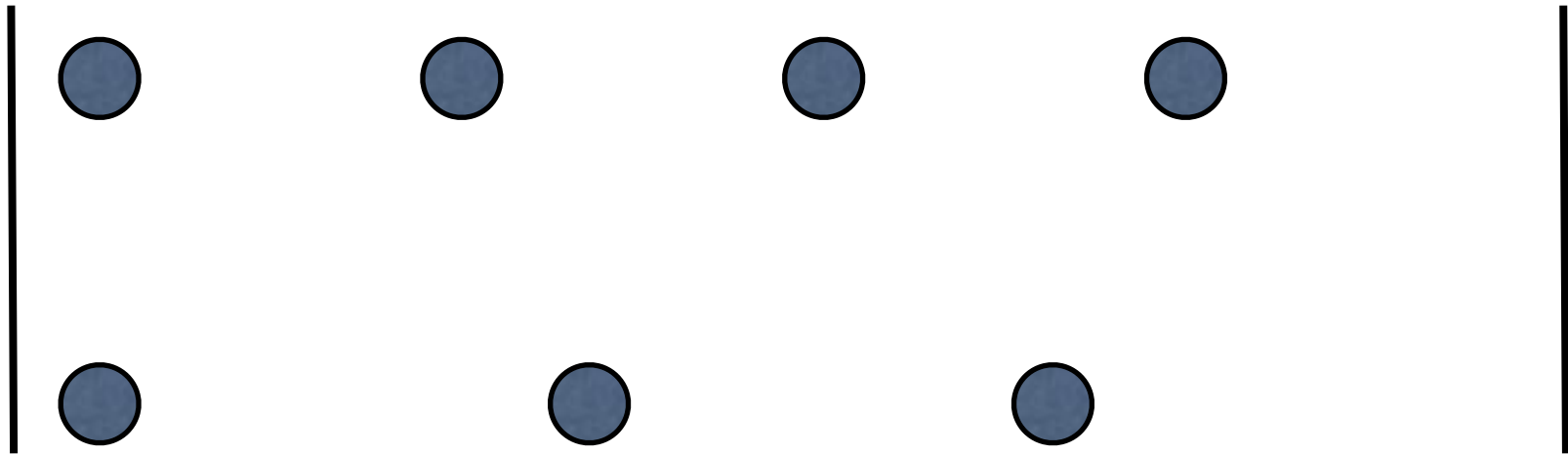
Why is it hard to pat your tummy and rub your head at the same time? Why is it much harder to do so with each hand moving at a different rate?

1	2	3	4	5	6
X		X		X	
X			X		



“Nice cup of tea”

# A harder one....



“Eat your goddamn spinach”

# Time to Think!!

*A motor program* is (was?) a concept frequently used in explaining action.

In what ways might this metaphor (computer program -- motor program) be misleading?

## Program:

A central executive *instructs* subservient parts as to what they are to do and when.

The chain of *command* is from the centre to the periphery, although some role for feedback might be included.

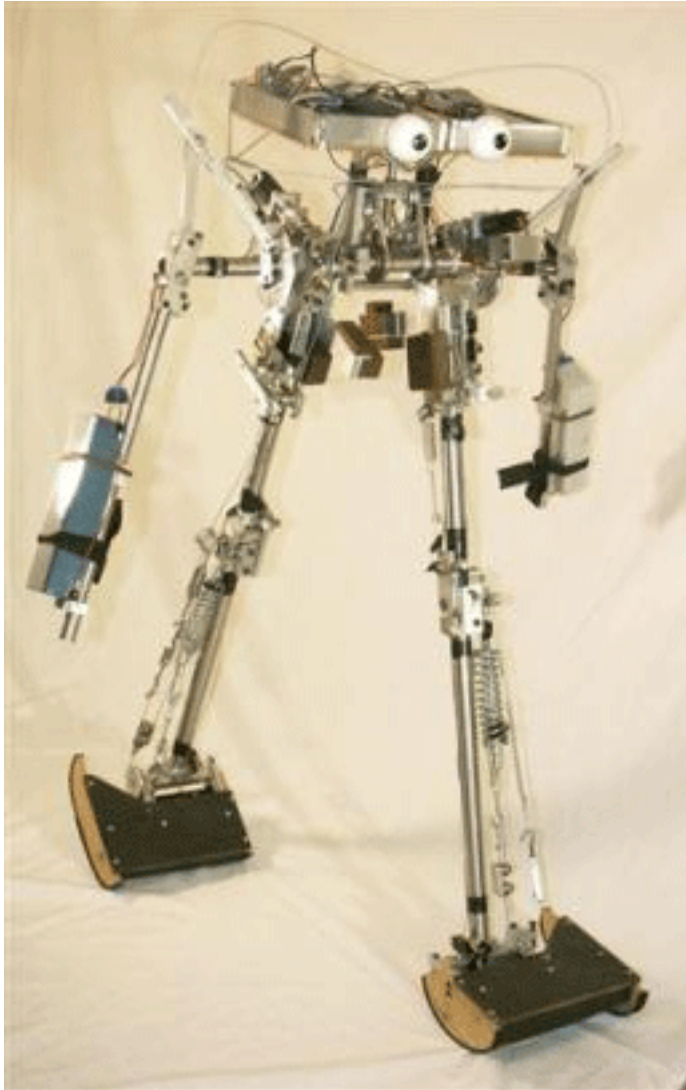
Using the 'program' metaphor, there appears to be a fundamental divide between the different parts of the system, and between the system and the environment.



There is no simple chain of  
command  
Brains are massively recurrently  
connected, with feedback loops  
everywhere



# Testing Theories: Building Robots



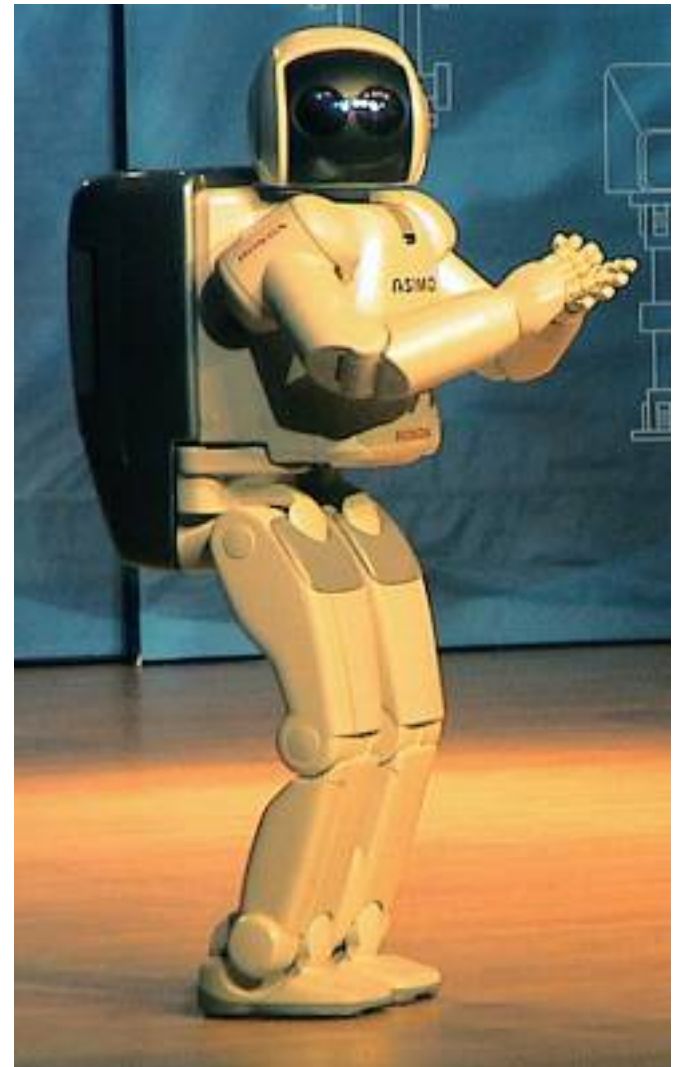
Cornell



Rodney Brooks: Ghengis



iCub: [www.robotcub.org](http://www.robotcub.org)



Asimo





# Big Dog, Boston Dynamics, 2010



# Atlas, 2016







Handle, February 2017. Note endpoint control.

<https://www.youtube.com/watch?v=-7xvqQeoA8c>

Founded in 1992, Boston Dynamic's research was almost all classified, as it was developed exclusively for the military

In 2013, Google bought Boston Dynamics.

Mission: To search ... and destroy?

In 2013, it was sold on to a Japanese Bank.

# Serial Order

Locomotion is roughly periodic.

Coordination is largely a matter of aligning the relative phase of several oscillators.

More complex actions are not simply periodic.

For example, speech is not simply repetitive, but requires complex sequences of movements in accordance with the regularities of a language



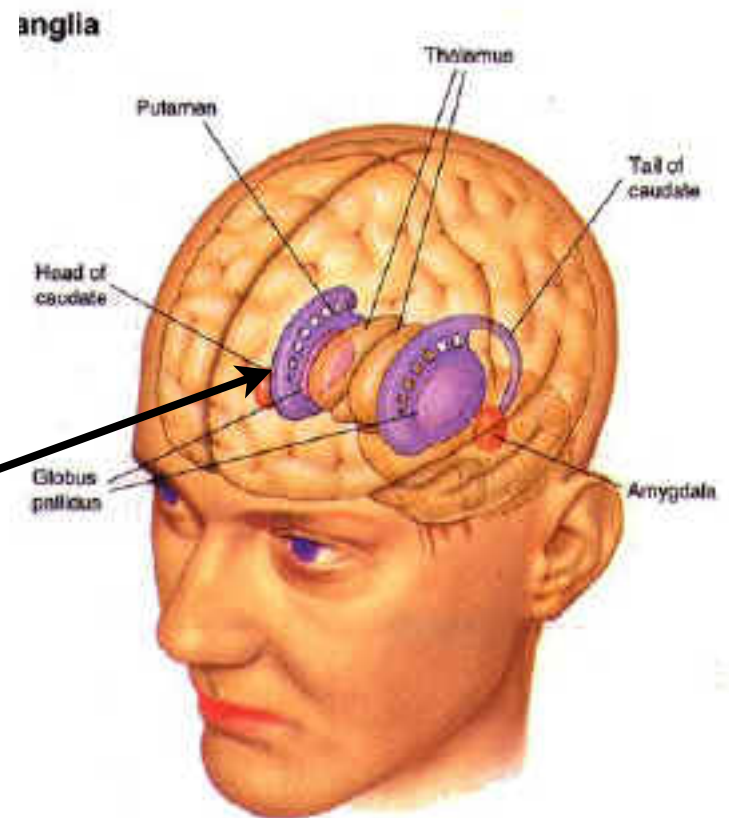
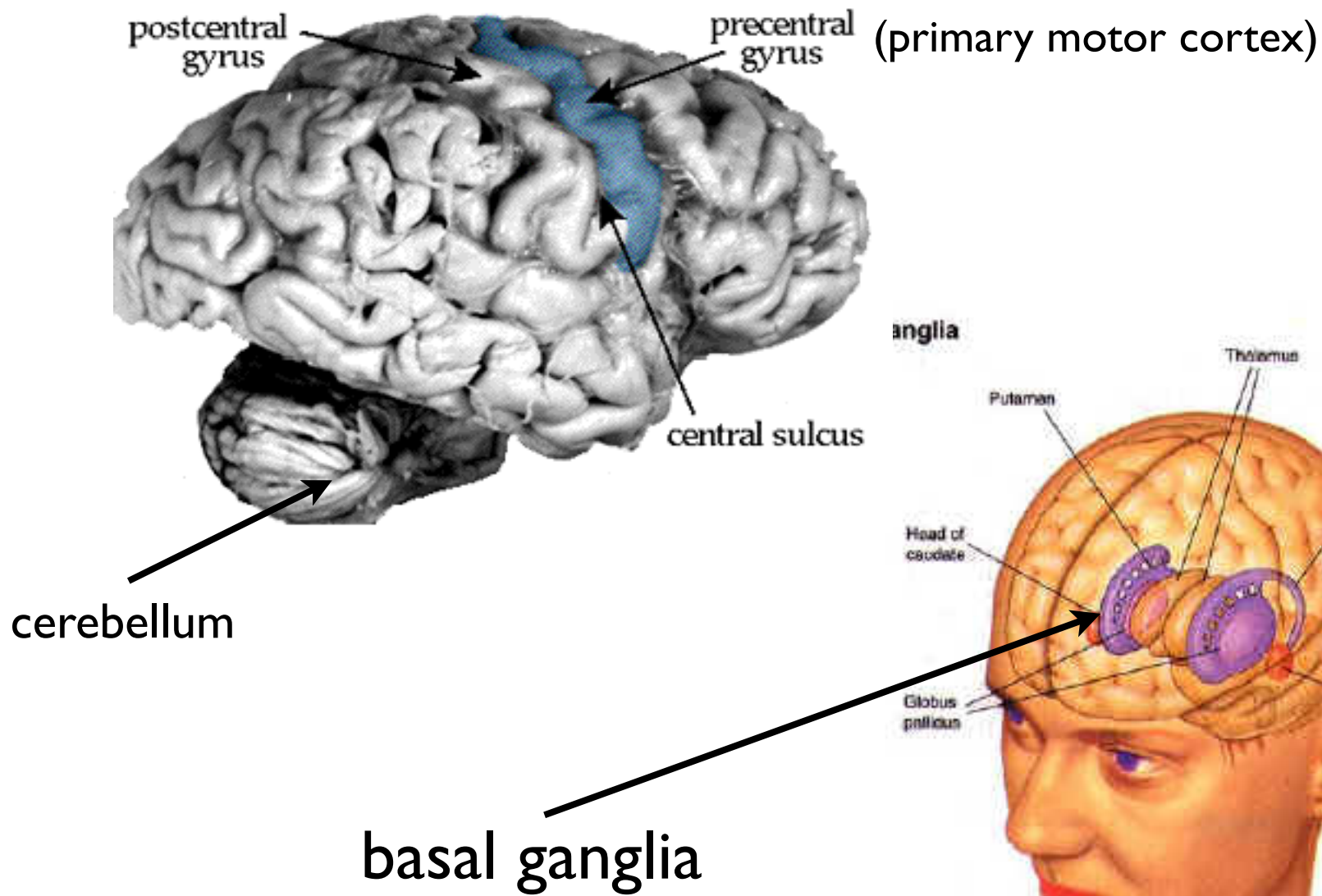
# Rodent Grooming has its own Syntax

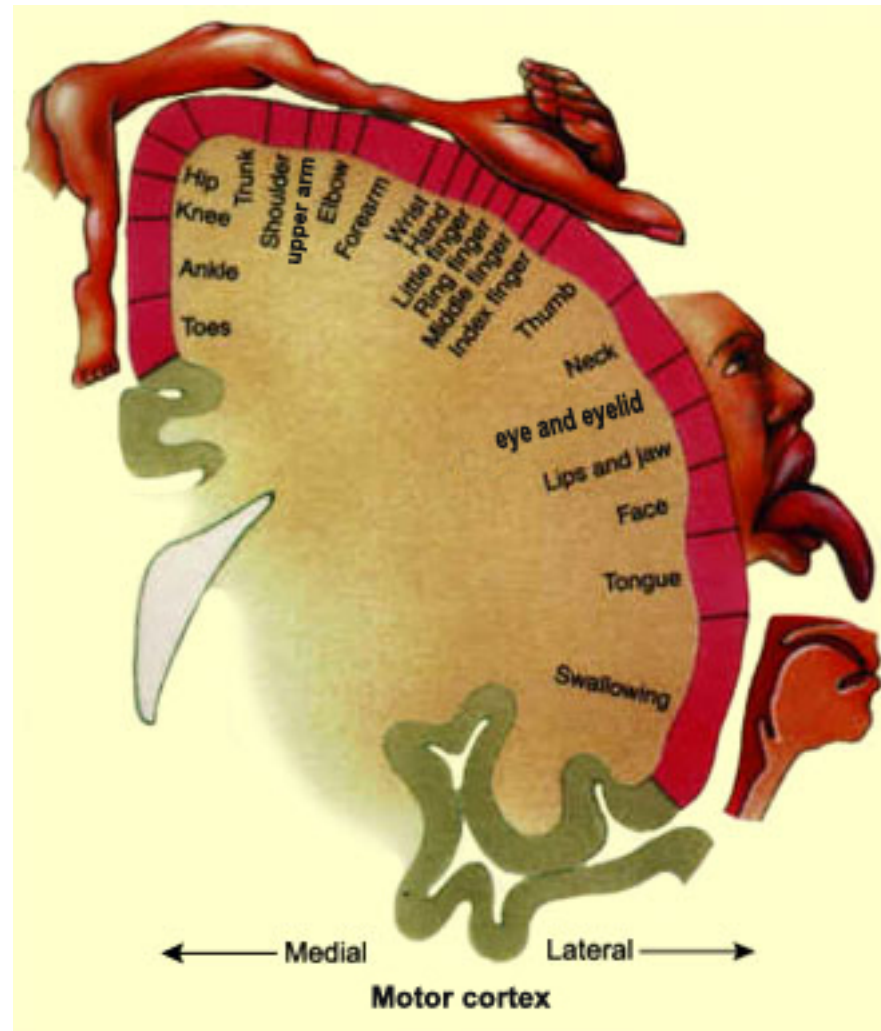
Specific nerve bundles have been identified that code the sequence (rather than its parts)

There may be common abstract principles underlying even such complex behavior as speaking, if we view syntax as a matter of sequencing and coordination



# **Principal parts of the nervous system involved in movement...**





Motor cortex

Principal source of nerve impulses to muscles

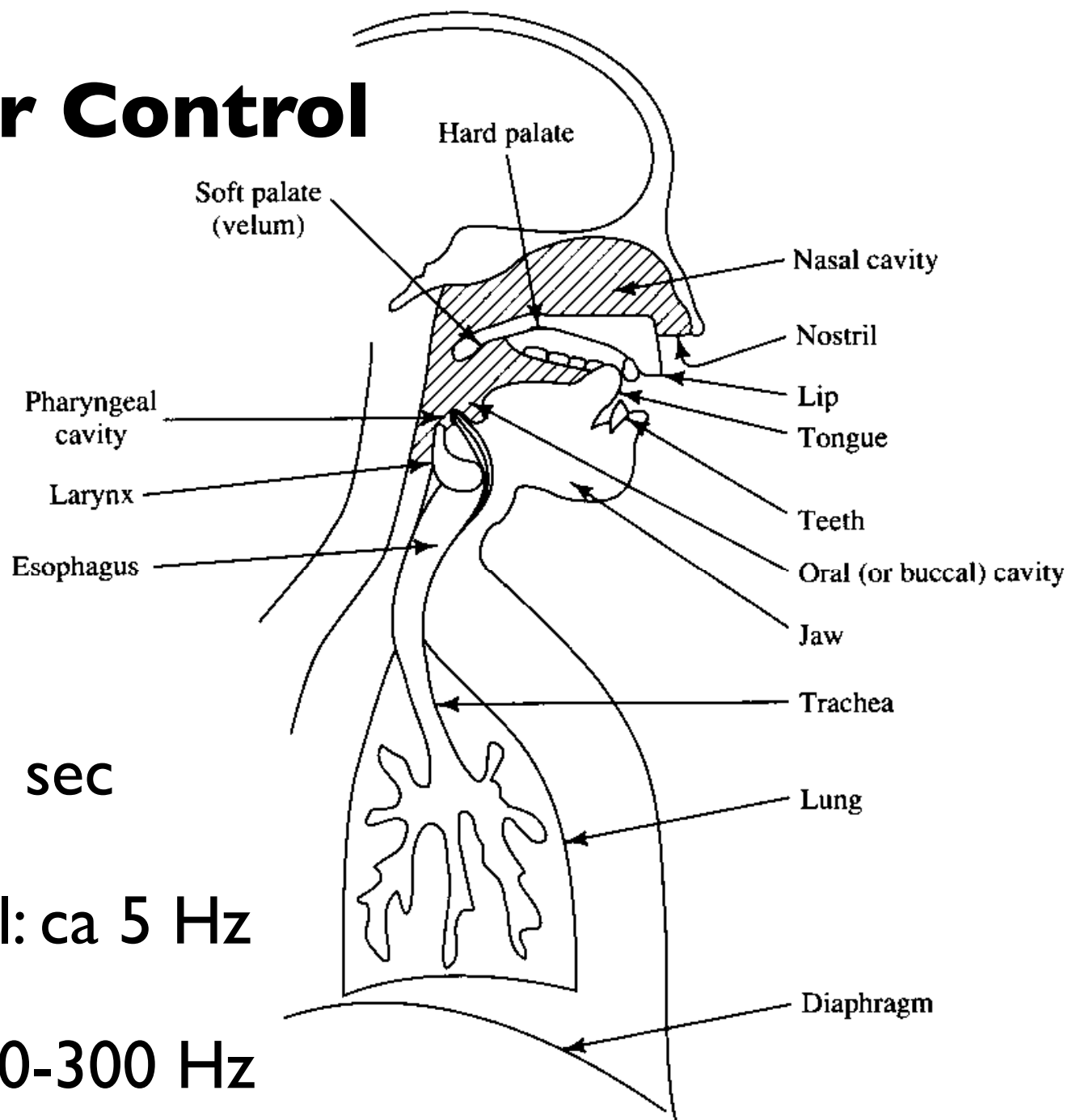
Cerebellum

Stability, posture, control of well learned coordinations

Basal ganglia

Sequencing and fine tuning of sequences of skilled actions

# Speech Motor Control



Breath control:  $> 1$  sec

Articulator control: ca 5 Hz

Glottal vibration: 80-300 Hz

Figure 1.1 The human vocal tract and speech production mechanism

# Is speech movement special?

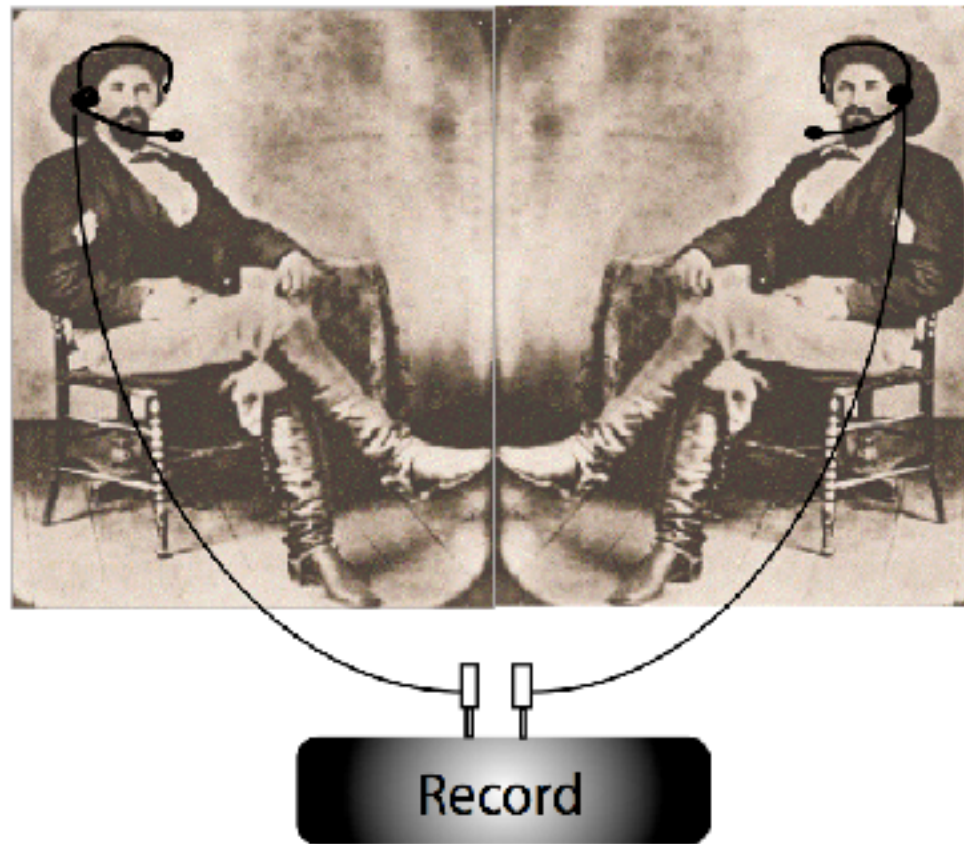
Moving parts (articulators) are in relative isolation from the outside environment

Coordination of movement at a vast range of timescales, from very fast to quite slow (breathing)

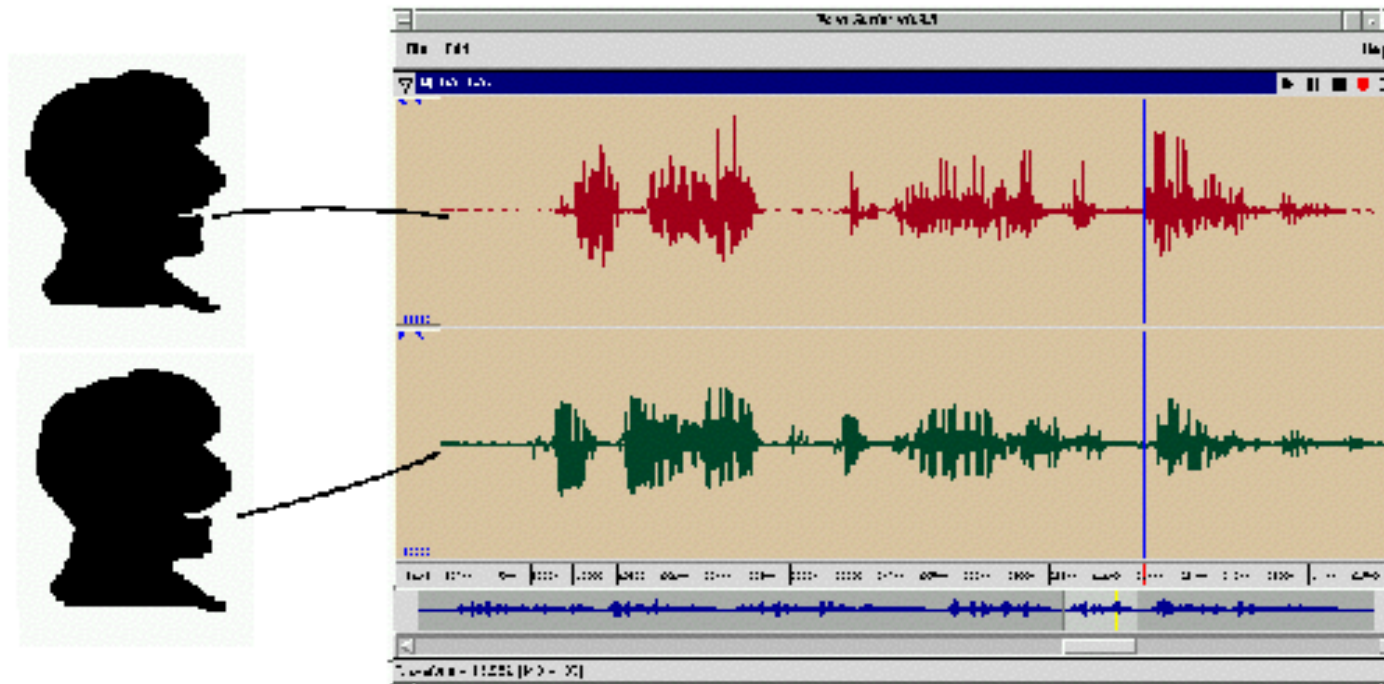
Must manage to convey symbolic, discrete information at a high transmission rate



# An Interesting Puzzle: Synchronous Speech





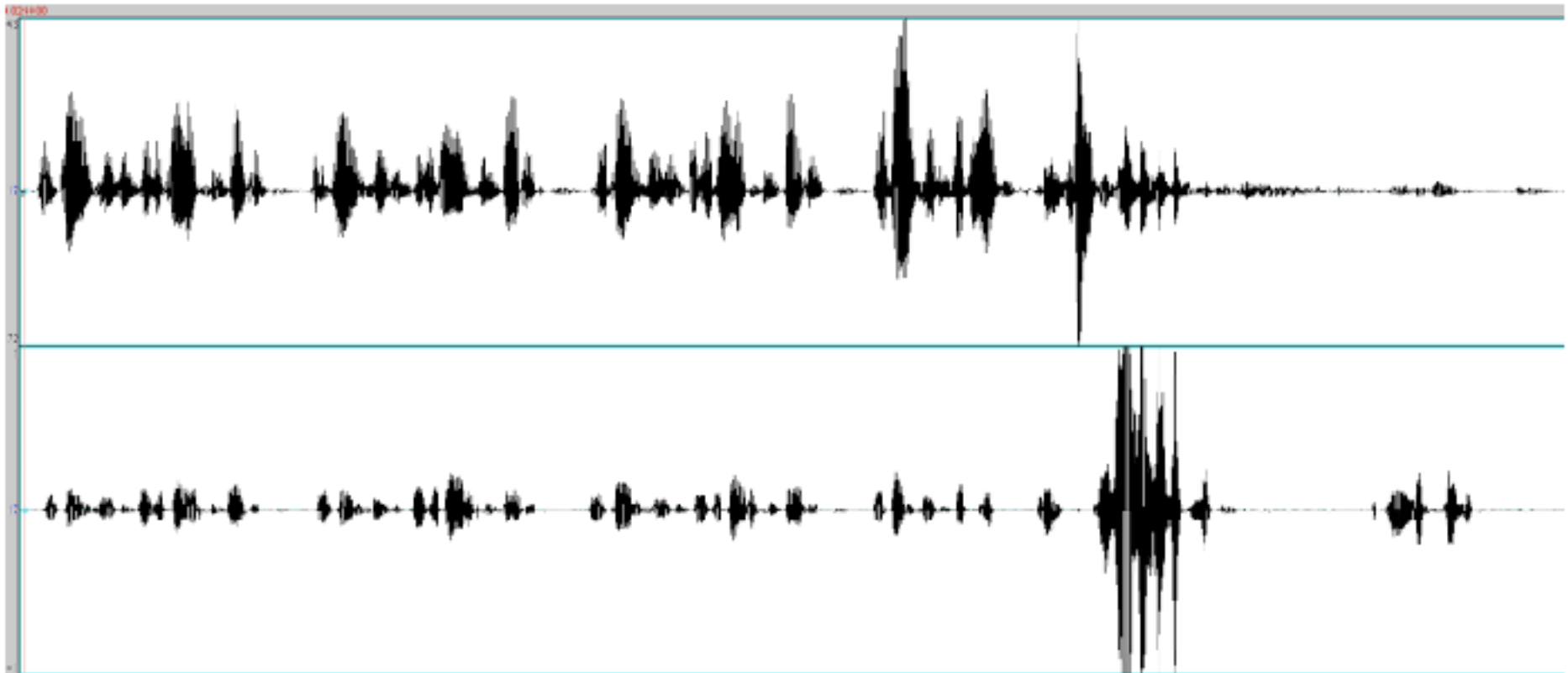


Synchrony is very tight: typical asynchrony  $\sim 40$  ms.

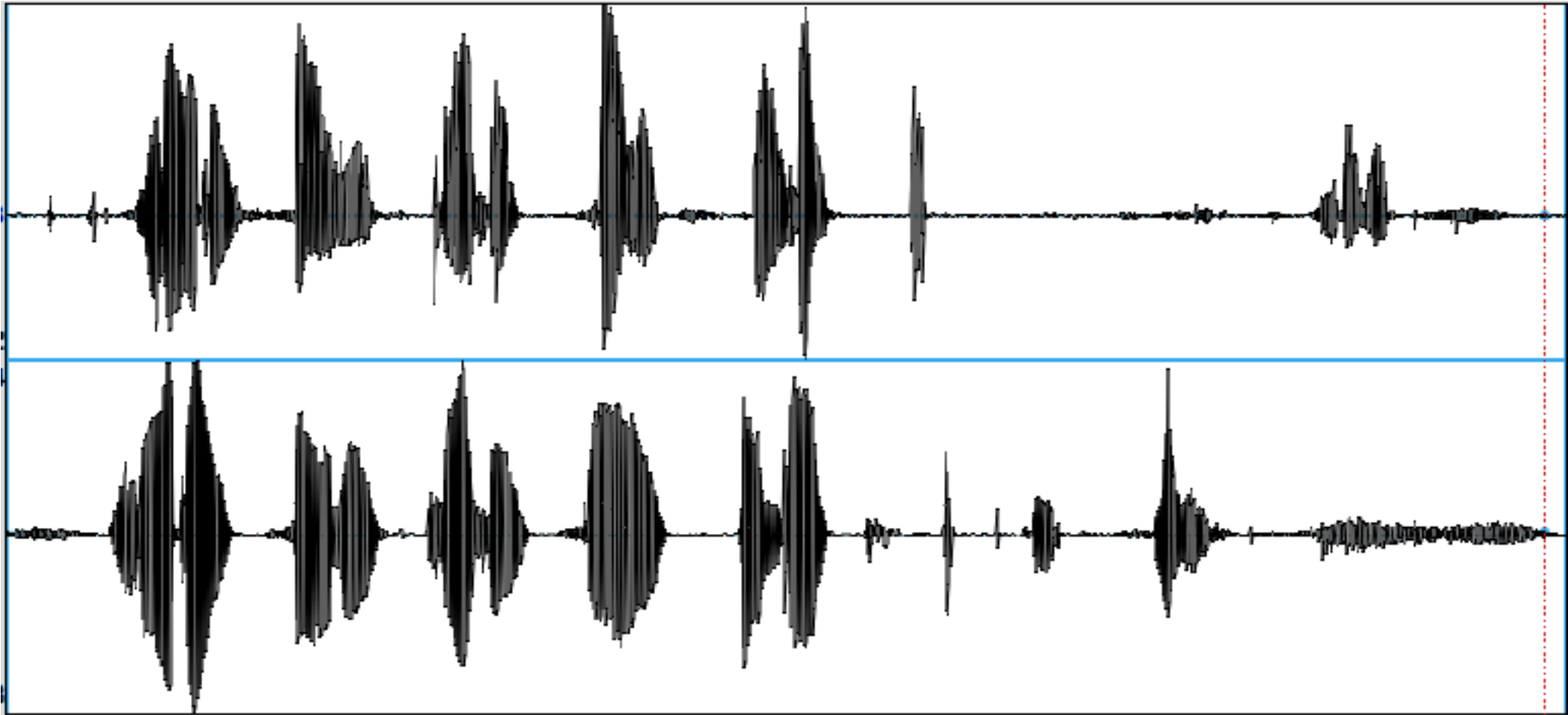
No periodic basis!

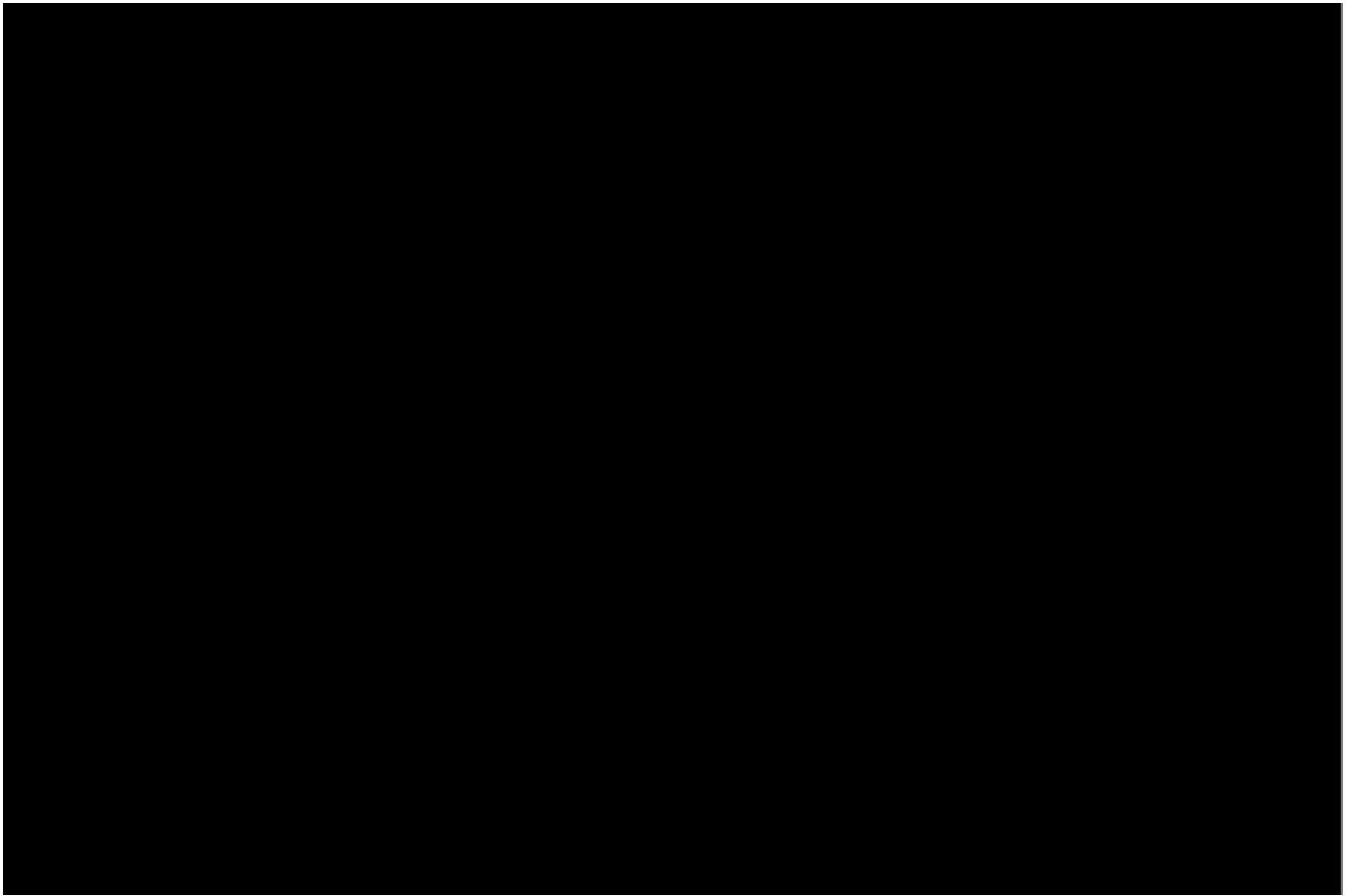


# Disintegration of a 2-person coordinative domain



## Example 2





# Coda: Synchronization and Creativity

(If you are viewing the slides, there was a dolphin video here in the lecture)